## Reactive Power Control Relay <br> EMR 1100 /-S <br> Operating Instructions

Fig. 1: View of Front Panel


Figure 1: View of Front Panal

Fig. 2: View from below


Figure 2: View from below
Contents Page

1. Summary of Instructions ..... 7
2. Functions ..... 8
2.1 Device version ..... 8
2.2 Automatic Identification of Voltage and Current Source. ..... 8
2.3 Automatic Identification of the Connected Capacitor Stages ..... 9
2.4 Automatic Setting of Switching Time Delay ..... 10
2.5 Power Feedback ..... 10
2.6 Tariff Switching *) ..... 10
2.7 Bus Connection *) ..... 10
3. Installation and Connection ..... 11
3.1 Installation ..... 11
3.2 Supply Voltage Connection ..... 11
3.3 Current Transformer Connection ..... 12
3.4 Measuring Voltage Connection ..... 12
3.5 Alarm Contacts ..... 13
3.6 Control Contacts ..... 13
3.7 Tariff Switching Connection *) ..... 13
3.8 FRAKO Power Bus Connection *) ..... 14
3.9 Additional Instructions ..... 15
4. Commissioning ..... 16
4.1 First Commissioning ..... 16
4.2 Renewed Commissioning ..... 16
5. Programming (Set) ..... 17
5.1 Setting of Target Power Factor Tariff 1 ..... 22
5.2 Parallel Shift (PS) Tariff 1 ..... 23
5.3 Limitation (L) Tariff 1 ..... 23
5.4 Switching Time Delay Tariff 1 ..... 25
5.5 Target Power Factor Setting Tariff 2 ..... 25
5.6 Parallel Shift (PS) Tariff 2*) ..... 25
5.7 Limitation (L) Tariff 2*) ..... 25
Page
5.8 Switching Time Delay Tariff 2*) ..... 25
5.9 Automatic Stage Current (c/k) Identification "ON/OFF" ..... 26
5.10 Response Current (c/k) ..... 26
5.11 Switching Sequence ..... 28
5.12 Number of Contactors used ..... 28
5.13 Specifying fixed Stages ..... 28
5.14 ON/OFF Connection Identification ..... 29
5.15 Connection Mode ..... 29
5.16 Setting Capacitor Discharge Time ..... 29
5.17 Setting Cyclic/Non-Cyclic Switching Rotation ..... 29
5.18 Current Transformer (CT) Ratio ..... 29
5.19 Voltage Transformer Ratio ..... 29
5.20 FRAKO Power Bus Address. ..... 30
5.21 Setting $5^{\text {th }}$ Harmonic Threshold ..... 30
5.22 Setting $7^{\text {th }}$ Harmonic Threshold ..... 30
5.23 Setting $11^{\text {th }}$ Harmonic Threshold ..... 30
5.24 Setting $13^{\text {th }}$ Harmonic Threshold ..... 30
5.25 Harmonic Over-Current Alarm Signal ..... 30
5.26 Setting Threshold for Number of Switchings Alarm ..... 31
5.27 Reseting Switching Counter ..... 31
5.28 Suppressing the PF Alarm ..... 31
5.29 Total kvar Display ..... 31
6. Operation ..... 32
6.1 Modes of Display ..... 32
6.2 Manual Operation ..... 33
6.3 Alarms ..... 34
7. Technical Data ..... 36
8. Trouble-Shooting ..... 38
*) only possible at full version

- The user must make sure that every person handling this unit must know these operating instructions and handle the unit accordingly.
- These operating instructions must be read thoroughly before the unit is installed and commissioned.
- Proceed only according to these operating instructions.
- Only trained personnel should install and commission this unit. Specific rules and regulations must be observed.
- The unit is under power and must not be opened.
- If the unit is visibly damaged it must not be installed, connected and commissioned.
- Disconnect the unit immediately if it does not operate after commissioning.
- Do observe all laws and regulations concerning this product.

Additionally all safety and commissioning instructions of the Reactive Power Control System are to be observed.

# EG-Konformitätserklärung <br> Declaration of Conformity 

Dokument-Nr.: EG-EMR-101A / 07.2002
WridWe $\quad$ FRAKO Kondensatoren- und Anlagenbau GmbH
Tscheulinstraße 21 a
79331 Teningen
GERMANY
erklären in alleiniger Verantwortung, daß das Produkt declare under our sole responsibiity that the product

| Produktbezeichnung: <br> name of product | Bindleistungsregler EMR 1100 und EMR 1100-S <br> Power Factor Control System |
| :--- | :--- |
| Typenreihe: EMR ab Fert.-Nr. 002000 <br> family  from Ser. No. |  |

auf das sich diese Erklärung bezieht, mit der/den folgenden Norm(en) oder normativen Dokument(en) ubereinstimmt:
to which this doclaration relates is in conformity with the following standard(s) or other normative document(s):

1. EN $50081-1$
EN $50081-2$
EN $50082-1$
EN $50082-2$

gemaß der Bestimmungen der Richtlinien
following the provisions of Directive toflowing the provisions of Directive

gémäß der Bestimmungen der Richtinien
following the provisions of Directive
73/23/EWG Niederspannungsrichtinie / Low Voltage Directive

Teningen, den 26.07.2002


[^0]
## 1. Summary of Instructions

On delivery, the control relay is set to preprogrammed standard values.
(see Table 1, pages 18 to 20)
The Reactive Power Control Relay EMR 1100 is self-regulating (i.e. it detects and adjusts to the voltage phase connection, frequency and the response curent ( $\mathrm{c} / \mathrm{k}$ ratio) automatically).
Before a reactive power control system can be put into operation, the target power factor has to be programmed.

## How to programme the Control Relay:

a) The control relay should be connected as shown in (see page 12).
b) ) Apply voltage to the control relay: "---" appears on the digital display. The control relay now identifies the location of the current and voltage source. This process takes at least 2 minutes and a maximum of 15 minutes. The power factor is displayed. (If this is not the case, see section 8. page 38).
c) Press the "Set" button for 8 seconds. "-01-" will appear on the digital display and the "manual" LED flashes.
d) By repressing the "Set" button the target power factor is displayed. If necessary, reprogramme to the nearest higher or lower value by pressing either the "+" or "-" button until the required target power factor is displayed.

If no numbers appear on the display then the control relay must be briefly disconnected from the voltage source and the "Set" button has to be pressed again according to c ).
e) To confirm the value press the "Set" button again. "-02-" will appear on the display.
f) Now press the "-" button twice until "END" appears on the display. Store this value by pressing the "Set" button. The target power factor is now stored permanently.

To display the correct values for power and current, enter the current and voltage transformer ratios (see sections 5.18 and 5.19).
To prevent unintentional reprogramming, the set mode can only be activated within the first 5 minutes after the operating voltage has been applied. If the set mode has been activated within the first 5 minutes, you have one hour to complete the programming. In order to obtain the set mode again after this period of time the control relay must be briefly disconnected from the voltage source.

On pages 18-20 all other preprogrammed standard values and their programme ranges are listed. The function of the preprogrammed standard values is described under section 5 .

## 2. Functions

The reactive power and active power portions of the power source are continuously calculated in the control relay from the measured voltage and the signals of the current transformer. If the reactive power portion exceeds certain threshold values, which the control relay has measured at the time of auto-adaption or are set as per section 5 , a switching action will take place at the switching outputs.
In the case of inductive reactive current (inductive reactive power) one or more control contacts of the reactive power control relay are closed after the preprogrammed time delay.
This causes the EMR 1100 to switch capacitor stages onto the power source supply, as and when required, in order to achieve the programmed target power factor. If the inductive reactive current portion of the load is reduced, the excess of reactive current causes the capacitor stages to be switched off line.
The Control Relay EMR 1100 allows a variety of possible settings to meet the conditions on site. The relay's cyclic operations prolong the life of all connected devices by averaging the length of time the capacitor stages are switched on. An effective supervision of the reactive power control system (capacitor bank) is secured by the power factor display.

### 2.1 Device version

The Control Relay EMR 1100 is availaby as a basic version (-S) and a full version. During the power up of the Control Relay, the software version and the device version are shown at the display:
i.e.: basic version (-S)

$$
\begin{aligned}
& ==\begin{array}{c}
\text { software version V2.00 } \\
\text { full version }
\end{array}
\end{aligned}
$$

The basic version has the following reductions:

- no bus- or serial connection possible only settings for tariff 1 available

The basic version can be enlarged by an update-key for the full version any time. (see accessories, section 7)

### 2.2 Automatic Identification of Voltage and Current Source

When voltage is initially applied to the control relay, it determines the location of the current and voltage sources (automatic phase rotation), i.e. it identifies in which phase and at which phase angle the current path and the voltage path are connected. Should the control relay fail to identify the current and voltage source due to power instabilities, repeat the procedure when the power has stabilized. It is also possible to programme the phasing manually (see sections 5.14 and 5.15).

Resetting of the control relay and reidentification of voltage and current sources is initiated by pressing buttons "+" and "Set" simultaneously for at least 8 seconds.

### 2.3 Automatic Identification of the Connected Capacitor Stages

Having determined the voltage and current source identification, the EMR 1100 automatically calculates the $\mathrm{c} / \mathrm{k}$ identification. During the identification process all the control contacts of the relay are individually switched on and off again. The stage currents ascertained are then stored. These values determine the stage sequence. In this way it can also be determined which switching outputs are in use.

The processes of automatic identification of voltage and current source and/or the automatic identification of capacitor stages are only carried out when switching on or pressing the combination of buttons "+", "-" and "Set" for min. 8 seconds.
(see section 2.1)
Precondition: The automatic identification mode or the automatic identification of connected capacitor stages mode are switched to "ON".

The EMR 1100 checks stored stage currents at specific time intervals during normal operation. If it recognises that a capacitor stage has failed, this stage (stage without capacitance) will be ignored in future normal operations.
All failed stages are switched on from time to time in order to re-check their capacitance. If a capacitor stage is added later on, or defective fuses are exchanged, the EMR 1100 itself identifies this after some time and the stage is then reintegrated into the normal operation. However, we recommend that if capacitor stages are added at a later date, the set-up procedure be repeated (see section 2.1).

## Note:

In case of low voltage networks being fed by several transformers switched in parallel, the capacitor current is distributed to all the transformers. If measurements are not carried out via a summation transformer, the current change, measured by the control relay, is too low when switching on the capacitor stages, which can lead to errors during the automatic stage identification process. In such situations we recommend that the stage identification be switched off and the relevant values be programmed manually. (see sections 5.9 to 5.12 )

### 2.4 Automatic Setting of Switching Time Delay

In order to keep the wear of the capacitor's contactors down to a minimum the response time of the control relay is lengthened or shortened automatically according to the frequency of the change of the load.

### 2.5 Power Feedback

The EMR 1100 is equipped with a four quadrant control. This means that even when active power is fed back into the mains, the control relay ensures compensation for the reactive power which has been drawn from the mains. In this case the LED "Regen" lights up.

### 2.6 Tariff Switching *)

The EMR 1100 offers the possibility to store two different target power factors (Tariffs $1 / 2$ ). These can be chosen through an external, potential free contact. It is therefore possible to achieve different switching actions (i.e. at high or low demand times or during normal operation and emergency power operations).

### 2.7 Bus Connection *)

The EMR 1100 is equipped with a 2-wire bus connection. It can therefore be connected to the FRAKO Energy Management System Central Unit EMIS 1500 series (which can be linked to a PC). All system data (voltage, current, harmonics, etc.), controller parameters, and settings for the EMR 1100 can be edited, changed, and printed via the PC connected to the Central Unit EMIS 1500.
The control relay can be connected to a PC or a PLC system via the Interface Unit EMP 1100 and all data will be available for controlling or editing.
Further information is available from
FRAKO or its agents and representatives.

[^1]
## 3. Installation and Connection

The Reactive Power Control EMR 1100 automatically determines the location of the current and voltage sources (automatic phase rotation). It may be connected either to two phases (phase / phase) or to one phase and neutral (phase/neutral).
The current transformer can be installed in any phase. It has to be passed by both capacitor and consumer current.

$A$

## IMPORTANT NOTICE:

During installation and service work the control relay must be kept free of voltage.

### 3.1 Installation

As accessories (protection kit; see section 7) insulated fixing screws are available. These can be used to install the control relay into switchgear cabinets of cubicles of protective class II. Furthermore a sealing ring is part of the protection kit, which must be used when installing the control relay in switchgear cabinets and cubicles of protection class IP 54.
The pre-mounted terminal connections allow a quick and easy installation. The control relay is electrically connected through a multiple connecting terminal supplied with the relay.

### 3.2 Supply Voltage Connection

The control relay should preferably be connected to the three-phase system as shown in (page 12). To keep the function "Zero Voltage Alarm" operational the supply voltage of the control relay should be connected in the same phase as the contactor voltage.

Supply voltage of 230 V should be connected between the terminals " $\mathrm{N} / \mathrm{L}$ " and " 230 V ". Supply voltage of 400 V should be connected at the terminals " $\mathrm{N} / \mathrm{L}$ " and "400V".

$A$IMPORTANT NOTICE:
The control relay is designed for a mains voltage of 230 VAC or 400 VAC (phase/neutral or phase/phase).
For voltages greater or equal to 400 V , a control transformer for the supply of the controller must be used.
It is not allowed to use both connecting terminals " 230 V " and " 400 V " simultaneously.
The connection of the supply voltage must be fused externally with max 4A.

Figure 3: Circuit Diagram


### 3.3 Current Transformer Connection

The outputs S1 and S2 of the current transformer are connected to the terminals S1 and S2 of the control relay. In order to keep the load on the current transformer as low as possible the supply lines should have a cross-section area of $2.5 \mathrm{~mm}^{2}$.

$\triangle$
ATTENTION:
The rated current in the current transformer path should not exceed 5 Amps.

## Notice:

After connection the short-circuiting bridge might have to be removed from the current transformer.

### 3.4 Measuring Voltage Connection

The EMR 1100 is equipped with a separate measuring voltage path. Therefore measuring voltage and supply voltage are separated (i.e. to measure at the medium voltage side).

A

## IMPORTANT NOTICE:

The control relay terminals of the measuring voltage must be externally protected by fuses.
The voltage path (measuring input) is suitable for voltages of 100 to 690 VAC only.

### 3.5 Alarm Contacts

A potenial-free alarm signal contact is accessible on the terminals "a" and "b". The contact closes when either there is no mains voltage applied to the control relay or when an alarm is signalled.(section 6.3) When there is an alarm signal, the LED "alarm" lights up and the relevant LED begins to flash on the control relay.

AIMPORTANT NOTICE:
It must not be possible to touch the applied voltage at the alarm contact. If this cannot be achieved the voltage must be earthed, even if it is only small protective voltage. The maximum load for the alarm contact is 250 VAC and 3 Amps.

[^2]
### 3.6 Control Contacts

The control voltage of the contactors should be connected to the terminals "PI" and "PII". These circuits are potential free.

AIMPORTANT NOTICE:
In order not to overload the control contacts the sum of the holding currents of all contactor coils connected may not exceed a value of 5 Amps.
The max. load of the switching contacts is 380 VAC.

In order to maintain the function of the undervoltage monitoring it is absolutely necessary to make sure that the control voltage of the contactors is in the same phase as the control relay supply.

### 3.7 Tariff Switching Connection *)

A different switching characteristic can be obtained by closing an external potential free contact.(see Tariff 2, Table 1)
Connection is done on terminals marked cos phi 1/2.

## Notice:

The connection of the tariff switching is connected to the FRAKO Power Bus connection. The external contacts must be potential-free as the 2-wire bus is centrally earthed. (Potential transient currents are possible.)

### 3.8 FRAKO Power Bus Connection *)

The EMR 1100 is configured for connection to the FRAKO Power Bus®.
It can also be connected to an RS 232 interface with an "RS232 adapter" (accessory; see section 7). The PC software "EMR-SW" (accessory) can be used as a user interface. (full version only)
The two poles of the 2 -wire bus are connected to terminals $A$ and $B$ (note polarity). The shielding is connected to one of the " $\perp$ " terminals.


Figure 4: FRAKO Power Bus®
Terminal " A " is therefore connected to all terminals "A" of the other devices connected to the bus. Terminal " B " is connected to all other terminals "B". Terminal " $\perp$ " is connected to all other terminals " $\perp$ ". ( Do not cross the wires!!)
The bus structure must be linear. All instruments must be looped in the string or
connected to it with a wiring. (up to 2 m ). Other bus structures can be realised with a repeater (accessory EMB 1101).
The overall length of the bus should not exceed 1200 m . A repeater (accessory EMB 1101) must be employed to bridge greater distances.
Terminal resistors must be employed at the beginning and end of a string.
A 120 Ohm resistor must be connected between the terminals " A " and " B ".
A 1 kOhm resistor must be connected between " A " and " $\mathrm{\perp}$ " in bus systems with less than 4 devices. The resistors must be suitable for 250 mW power.

## Note:

Never connect the shielding (" $\perp$ ") to the earth terminal of EMA 1101.

## Recommended cables

Characteristic impedance 100-120 ;
$\varnothing \geq 0,3 \mathrm{~mm}^{2}$; twisted and shielded;

## Types:

IBM Twinax $105 \Omega$

- Lapp Unitronic® Bus CAN $1 \times 2 \times 0,34$

Helukabel CAN BUS $1 \times 2 \times 0,34$
Note:
A mixture of different cable types must always be avoided.
*) only possible at full version

### 3.9 Additional Instructions

The installation and connection of the EMR 1100 is only finished, once it has been installed and wired according to these instructions.

[^3]
## 4. Commissioning

After the control relay has been installed as described in section 3, the relay can be put into operation.

### 4.1 First Commissioning

When the control relay is put into operation for the first time it tries to determine the mode of connection and the size of the stages. The display shows "---" and after a discharge time for the capacitors the stages are switched on and off again one after the other. This process can take up to 15 minutes.

## ATTENTION: <br> If the EMR 1100 does not act as described above, remove voltage source and check installation.

If the identification process is not concluded within 15 minutes there is probably a fault. (See section 8, page 38)

## Notice:

In order for the relay to be able to determine the mode of connection at least one capacitor stage must be operational.
Possibly the control relay has already been used before and acts as described in section 4.2.

It is also possible to discontinue the identification process by switching off the automatic connection and stage current identifications. This takes place in set mode and at the same time it is necessary to programme the connection and stage parameters manually (see section 5).

After the identification process the actual power factor appears on the display and the control relay begins to function. If the power factor shown does not coincide with the real power factor, the identification process must be repeated. This can be done by pressing the buttons "+", "-" and "Set" simultaneously for at least 8 seconds.

### 4.2 Renewed Commissioning

After a mains failure the control relay immediately starts the normal control programme again. The data which were determined whilst being put into operation for the first time are stored in a non-volatile memory.
By pressing the buttons "+", "-" and "Set" simultaneously for a least 8 seconds these data are erased from the memory and the control relay again begins to determine the mode of connection and the size of stages.
It is assumed that the automatic connection and stage current identification are switched on (see section 5).

## 5. Programming (Set)

In order to permit the widest possible use of the control relay, multiple settings are available. To simplify matters, the control relay is set to standard values in our factory before delivery. (see Table 1, pages 18 to 20)
The user only needs to change the target power factor or a few values to suit his special requirements. As a protection against unintentional reprogramming, the set mode (programming mode) can be invoked only within 5 minutes after operating voltage is applied. After this period the values can only be read (read-only mode). If the set mode has been activated within these 5 minutes, it remains available for one hour. In order to reach the set mode again after this period, it is necessary to disconnect the control relay from its source for a short period of time.

The procedure for checking or reprogramming the set values is as follows:

Man
Set

- Press the "man/set" button for at least eight seconds to switch to the set mode. The display then shows "-01-". This number corresponds to the first variable which is displayed or can be
changed in the following sequence (see Table 1).
- The actual value appears on the display when the "man/set" is pressed again.
■ By pressing the "+" or "-" button the next higher or lower setting can be attained.
The control relay is in the read-only mode if above is not possible. To reach the set mode again, the control relay must be disconnected from its source for a short period of time.
- Press the "man/set" button repeatedly; the mode numbers appear followed by the programmed value (see Table 1).
- If the "+" is pressed again after mode number "-29-" appears on the display, or if the "-" is pressed again after mode number "-01-" appears on the display, then the display will show "End".
- By confirming the display "End" by pressing the "man/Set" button the control relay assumes normal operation; the preset values are then permanently stored in a non-volatile memory.


## Notice:

During the "set mode" none of the capacitor stages is changed and there is no switching of the alarm contact.

Table 1: Programming of Values

| Programme <br> Mode No. | Description | Pre-programmed <br> standard Value | Programme Range |
| :---: | :--- | :---: | :--- |
| $-01-$ | Target Power <br> Factor Tariff 1 | Ind. 0.92 | from cap. 0.80 to ind. 0.80 in <br> increments of 0.01 steps |
| $-02-$ | Parallel Shift PS <br> (Tariff 1) | -1.0 (Target Power <br> Factor is lower <br> than limit value) | from -2 to +4 in increments <br> of 0.5 steps |
| $-03-$ | Limitation L <br> (Tariff 1) | +1.0 <br> (Overcompensation <br> is avoided) | from -2 to +2 in increments of <br> 0.5 steps |
| $-04-$ | Switching time <br> delay in sec- <br> onds Tariff 1*) | 45 | 5 to 500 seconds in 1 sec. steps <br> or at a high speed <br> in 5 sec.steps..*) |
| $-05-$ | Target Power <br> Factor Tariff 2*) | 1.00 | from cap. 0.80 to ind. 0.80 in <br> increments of 0.01 steps |
| $-06-$ | Parallel Shift PS <br> Tariff 2*) | 0.0 | from -2 to +4 in increments <br> of 0.5 steps |
| $-07-$ | Limitation L <br> Tariff 2*) | 0.0 | from -2 to +2 in increments of <br> 0.5 steps |
| $-08-$ | Switching time <br> delay in sec- <br> onds Tariff 2*) | 4500 seconds in 1 sec. steps |  |
| or at a high speed |  |  |  |
| in 5 sec.steps.**) |  |  |  |

*) settings only at full version possible
**) by pressing the buttons "+" or "-" for some time, the high speed mode will be activated.

Table 1 Programming of Values

| Programme Mode No. | Description | Pre-programmed standard Value | Programme Range |
| :---: | :---: | :---: | :---: |
| -11- | Switching sequence | 1:1:1:1:1 | $1: 1: 1: 1: 1 \ldots$ $1: 1: 2: 4: 4 \ldots$ $1: 2: 3: 4: 4 \ldots$ <br> $1: 1: 2: 2: 2 \ldots$ $1: 1: 2: 4: 8 . \ldots$ $1: 2: 3: 6: 6 \ldots$ <br> $1: 1: 2: 2: 4 \ldots$ $1: 2: 2: 2: 2 \ldots$ $1: 2: 4: 4: 4 \ldots$ <br> $1: 1: 2: 3: 3 \ldots$ $1: 2: 3: 3: 3 \ldots$ $1: 2: 4: 8: 8 \ldots$ |
| -12- | Number of contactors used | 12 | From 1 to 12 |
| -13- | Determination of Fixed stages | 0 | $\begin{aligned} & \hline 0=\text { no fixed stage } \\ & 1=\text { output fixed } \\ & 2=\text { outputs } 1 \text { and } 2 \text { fixed } \\ & 3=\text { outputs } 1 \text { to } 3 \text { fixed } \\ & \hline \end{aligned}$ |
| -14- | Automatic identification of voltage and current source | ON | $\mathrm{ON}=$ automatic OFF= manual When "ON", mode -15- can only be read but not changed. |
| -15- | Enter or read mode of connection | Automatic identification | See table 2 |
| -16- | Switching-off time | 60 | From 5 to 900 seconds. **) |
| -17- | Setting cyclic / non-cyclic switching rotation | ON | $\mathrm{ON}=$ cyclic switching OFF= non-cyclic switching |
| -18- | Current transformer Ratio | 1 | From 1 to 7000 in steps of 1 or at high speed in steps of $5 .{ }^{* *}$ ) |
| -19- | voltage transformer ratio | 1 | From 1 to 300 in steps of 1 or at high speed in steps of $5 .{ }^{* *}$ ) |

**) by pressing the buttons "+" or "-" for some time, the high speed mode will be activated.

Table 1 Programming of Values

| Programme Mode No. | Description | Pre-programmed standard Value | Programme Range |
| :---: | :---: | :---: | :---: |
| -20- | Bus number | 0 | From 0 to 125 (0 = no Bus function) |
| -21- | $5^{\text {th }}$ harmonic threshold in \% | 5 | From 1 to 20 \% in 0.1 \% steps or $0.5 \%$ steps at high speed.**) |
| -22- | $7^{\text {th }}$ harmonic threshold in \% | 4 | From 1 to 20 \% in $0.1 \%$ steps or $0.5 \%$ steps at high speed. ${ }^{* *}$ ) |
| -23- | $11^{\text {th }}$ harmonic threshold in \% | 3 | From 1 to 20 \% in $0.1 \%$ steps or $0.5 \%$ steps at high speed.**) |
| -24- | $13^{\text {th }}$ harmonic threshold in \% | 2.1 | From 1 to 20 \% in $0.1 \%$ steps or $0.5 \%$ steps at high speed. ${ }^{* *}$ ) |
| -25- | Harmonic over-current | 1.3 | From 1.05 to 3.0 times the nominal value or "H.-AL." in 0.05 steps or 0.1 increments at high speed |
| -26- | Threshold for number of switching alarm | 80 | From OFF to 1000 the value must be entered in $\times 1000$ switches |
| -27- | Cancelling individual switching counters | 0 | Enter a number of 1-12. When leaving this menu point the counter of the corresponding capacitor stage will be set to 0 . Point "ALL" will reset all counters to 0 . |
| -28- | Power factor alarm tripping signal | ON | ON or OFF <br> By setting "OFF" a power factor alarm can be suppressed. |
| -29- | Total kvar display | Will only be displayed when in operation | By pressing "set" button the total power in kvar will be displayed. |

${ }^{* *}$ ) by pressing the buttons "+" or "-" for some time, the high speed mode will be activated.

If the current transformer is installed in correct direction and the connections $\mathrm{S} 1(\mathrm{k})$ and S2(I) are correctly connected with the control relay, the following kinds of Connection modes are valid:

| Connection mode | Connection at the voltage path |  |  |
| :---: | :---: | :---: | :---: |
|  | L/N-L | L/N - L | L/N-L |
| 0 | L1-N | L2-N | L3-N |
| 1 | L1-L3 | L2-L1 | L3-L2 |
| 2 | N-L3 | N-L1 | N-L2 |
| 3 | L2-L3 | L3-L1 | L1-L2 |
| 4 | L2-N | L3-N | L1-N |
| 5 | L2-L1 | L3-L2 | L1-L3 |
| 6 | N-L1 | N-L2 | N-L3 |
| 7 | L3-L1 | L1- L2 | L2-L3 |
| 8 | L3-N | L1 - N | L2-N |
| 9 | L3-L2 | L1-L3 | L2-L1 |
| 10 | $\mathrm{N}-\mathrm{L} 2$ | N-L3 | N - L1 |
| 11 | L1-L2 | L2-L3 | L3-L1 |
| CT Location in phase: | $\begin{aligned} & \uparrow \uparrow \\ & \mathbf{L} 1 \end{aligned}$ | $\begin{aligned} & \uparrow \uparrow \\ & \text { L2 } \end{aligned}$ | $\begin{aligned} & \hline \uparrow \\ & \text { L3 } \end{aligned}$ |

Table 2: Connection mode

## Note:

If $\mathrm{S} 1(\mathrm{k})$ and $\mathrm{S} 2(\mathrm{I})$ are connected the wrong way around or the CT is installed in wrong direction, connection mode number must be added by 6 . If the result is higher than 11, 12 must be subtracted. The result corresponds to the connection mode number which have to be entered.

### 5.1 Setting of Target Power Factor Tariff 1

The desired target power factor can be set from cap. 0.80 to ind. 0.80 in 0.01 steps. The mode of operation of this adjustment can be seen in Figure 5 and Figure 6.

If the control relay operates within the band range shown no switching operations will be activated.
However, if the control relay operates outside the band range, the EMR 1100 will try to come within the band range with the minimum of switchings.

Figure 5: Control response after setting target power factor $=1 ; L=O F F ; P S=0$


Figure 6: Control response after setting target power factor $=0.92$ ind; $\mathrm{L}=\mathrm{OFF}$; PS = 0


In Figure 6 the behaviour of the control relay during feedback operation can also be seen. The "kink" in the band (characteristic line) is not reflected in the feedback operation but is extended at the point of intersection of the reactive power centre line (axis) with the feed-back operation line.
By shifting the band into the capacitive range (see Figure 8 in section 5.2) the occurrence of an inductive reactive power during the feedback operation can be virtually avoided.
When a capacitive target power factor mode is set, the control band is reflected from the supply side to the feedback side. (see Figure 11).

### 5.2 Parallel Shift (PS) Tariff 1

This setting causes a parallel shift of the band range as shown in Figure 5 by the set value.
It will shift to the inductive direction if the plus sign is used and to the capacitive direction if the minus sign is used.

The values -2 to +4 can be set in 0.5 steps. The effects are illustrated by the two examples in Figure 7 and Figure 8.

Figure 7: Control response after setting target power factor $=1 ; L=O F F$; PS = +1.0


The set target power factor is therefore the upper limit of the control band.

Figure 8: Control response after setting target power factor $=0.92$ ind; $\mathrm{L}=\mathrm{OFF}$;
PS = -1.0


The set target power factor is the lower limit of the control band range.
(This is the recommended setting when using asynchronic generators in parallel.)

### 5.3 Limitation (L) Tariff 1

This setting gives new possibilities that could not be attained before due to opposing requirements.

The range of values for $L$ are -2 to +2 in steps of 0.5 and the setting "OFF". Setting the limitation value of 1 and a target power factor of 1.0 has the same effect as the parallel shift. For a target power factor other than 1.0 there is a "kinked" characteristic as shown in Figure 9.

The limitation therefore specifies an absolute reactive power limit, below which the control band does not go.

Figure 9: Control response after setting target power factor $=0.92$ ind; $\mathrm{PS}=0$;
Reactive current
This setting has the following effects:

- The power factor is attained, on the average, in the "upper" power range.
- Over-compensation (capacitive load) is avoided in the low load range.

An appropriate combination of "parallel shift" and "limitation" is illustrated in Figure 10.

Figure 10: Control response after setting target power factor $=0.92$ ind; PS = -1.0; $\mathrm{L}=+1.0$


This example illustrates:

- In the "upper" power range the set power factor is specified as the lower limit value.
- Over-compensation is avoided in the low load range.

This setting is the normal setting on delivery from the factory and represents the best possible control characteristic for most applications.

The following Figure 11 shows the characteristics of the control band when set for a capacitive target power factor. In
this case the control range is not prolonged at the reactive power axis into the feed back side, but is mirrored from the supply side into the feedback side.

Figure 11: Control response after setting target power factor $=0.95 \mathrm{cap} ; \mathrm{L}=1.0$; PS = 0


### 5.4 Switching Time Delay Tariff 1

The switching time delay period can be set between the values of 5 to 500 seconds in 5 second steps. When a capacitor stage is switched on or off the control relay waits for the switching time delay before the switching process takes place. If more stages are required the switching time delay is shortened depending on the number of stages required.

## For example:

2 stages required $=$ switching time delay $/ 2$ (reduced by one-half) or
3 stages required $=$ switching time delay $/ 3$ (reduced by two-thirds).
In order to keep the wear on the contacts to a minimum, the switching delay time should be set to less than 45 seconds only in exceptional cases. The discharge period, which ensures that the capacitors are fully discharged before they are switched on again, overrides the switching delay time (see section 5.16).

### 5.5 Target Power Factor Setting Tariff 2*)

The same settings as described in section 5.1 apply for tariff 2.

### 5.6 Parallel Shift (PS) Tariff 2*)

The same settings as described in section 5.2 apply for tariff 2.

### 5.7 Limitation (L) Tariff 2*)

The same settings as described in section 5.3 apply for tariff 2.

### 5.8 Switching Time Delay Tariff 2*)

The same settings as described in section 5.4 apply for tariff 2.
*) only possible at full version

### 5.9 Automatic Stage Current (c/k) Identification "ON/OFF"

The EMR 1100 has an automatic c/k identification, i.e. it calculates the appropriate response current the first time the control relay is energized. This procedure is repeated until the amount of capacitive power for each stage is determined and the $c / k$ value has been calculated. The automatic $\mathrm{c} / \mathrm{k}$ identification feature can be set to "ON" or "OFF".
When "ON" the EMR 1100 operates with the stage currents automatically calculated. When "OFF" the c/k value must be programmed manually (under programme mode 10) according to Table 3 on page 27 or according to the Equation 1. Also programme modes 11 (switching sequence) and 12 (number of contactors used) have to be entered manually.

### 5.10 Response Current (c/k)

The Control Relay EMR 1100 calculates a control characteristic from the power factor, the parallel shift and the limitation (in Figure 5 to Figure 11 shown as a dotted line) and has a tolerance band of 0.65 times the smallest stage in inductive as well as in capacitive direction (marked with bold line). The control relay consistently achieves this control band by switching on and off systematically. It is assumed that the connected capacitorstages are sufficiently dimensioned.

The response current corresponds to half the width of the tolerance band, within which the reactive current can change without capacitor stages being switched on or off.
This is essential to ensure that the system does not oscillate. The total width of the tolerance band is selected in such a way that it corresponds to approx. 1.3 times the reactive current of the smallest capacitor stage.
When setting the automatic stage current identification to "OFF" the response current can be set between 0.02 and 2.0 A in steps of 0.01 A . The correct setting for a 400 V voltage system and a current transformer with 5 A secondary current can be taken from Table 3.
In the case of other voltages or current transformers for which the primary or secondary current is not given, the response current can be calculated from the general equation:
Equation 1:
$c / k=0.65 \times \frac{Q}{U \times \sqrt{3} \times k} \approx 0.375 \times \frac{Q}{U \times k}$
$c / k=$ response current (Amps) to be set
$Q=$ capacitor stage rating in var of the smallest stage (not the complete system)
$U=$ mains voltage $(\mathrm{V})$ on the primary side of the current transformer
$k=$ transformer ratio (primary /secondary current)

Table 3: Response Current at 400V mains voltage ( $\mathrm{c} / \mathrm{k}$ value)

|  |  | c/k-adjustment for mains voltage 400 VAC, 50 Hz ~ Stage rating of the smallest capacitor bank (not total rating |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Current transformer |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| A/A | 2,5 | 5 | 6,25 | 7,5 | 10 | 12,5 | 15 | 20 | 25 | 30 | 40 | 50 | 60 | 100 |
| $30 / 5$ | 0,40 | 0,80 | 0,98 | 1,20 | 1,60 |  |  |  |  |  |  |  |  |  |
| $40 / 5$ | 0,30 | 0,60 | 0,74 | 0,90 | 1,20 | 1,50 |  |  |  |  |  |  |  |  |
| $50 / 5$ | 0,24 | 0,48 | 0,59 | 0,72 | 0,96 | 1,20 | 1,44 |  |  |  |  |  |  |  |
| $60 / 5$ | 0,20 | 0,40 | 0,49 | 0,60 | 0,80 | 1,00 | 1,20 | 1,60 |  |  |  |  |  |  |
| $75 / 5$ | 0,16 | 0,32 | 0,39 | 0,48 | 0,64 | 0,80 | 0,96 | 1,28 | 1,60 | 1,92 |  |  |  |  |
| $100 / 5$ | 0,12 | 0,24 | 0,30 | 0,36 | 0,48 | 0,60 | 0,72 | 0,96 | 1,20 | 1,44 | 1,92 |  |  |  |
| $150 / 5$ | 0,08 | 0,16 | 0,20 | 0,24 | 0,32 | 0,40 | 0,48 | 0,64 | 0,80 | 0,96 | 1,28 | 1,60 | 1,92 |  |
| $200 / 5$ | 0,06 | 0,12 | 0,15 | 0,18 | 0,24 | 0,30 | 0,36 | 0,48 | 0,60 | 0,72 | 0,96 | 1,20 | 1,44 |  |
| $250 / 5$ | 0,05 | 0,10 | 0,12 | 0,14 | 0,19 | 0,24 | 0,29 | 0,38 | 0,48 | 0,58 | 0,77 | 0,96 | 1,15 | 1,92 |
| $300 / 5$ | 0,04 | 0,08 | 0,10 | 0,12 | 0,16 | 0,20 | 0,24 | 0,32 | 0,40 | 0,48 | 0,64 | 0,80 | 0,96 | 1,60 |
| $400 / 5$ | 0,03 | 0,06 | 0,08 | 0,09 | 0,12 | 0,15 | 0,18 | 0,24 | 0,30 | 0,36 | 0,48 | 0,60 | 0,72 | 1,20 |
| $500 / 5$ | 0,02 | 0,05 | 0,06 | 0,07 | 0,10 | 0,12 | 0,14 | 0,19 | 0,24 | 0,29 | 0,38 | 0,48 | 0,58 | 0,96 |
| $600 / 5$ |  | 0,04 | 0,05 | 0,06 | 0,08 | 0,10 | 0,12 | 0,16 | 0,20 | 0,24 | 0,32 | 0,40 | 0,48 | 0,80 |
| $750 / 5$ |  | 0,03 | 0,04 | 0,05 | 0,06 | 0,08 | 0,10 | 0,13 | 0,16 | 0,19 | 0,26 | 0,32 | 0,38 | 0,64 |
| $1000 / 5$ |  | 0,02 | 0,03 | 0,04 | 0,05 | 0,06 | 0,07 | 0,10 | 0,12 | 0,14 | 0,19 | 0,24 | 0,29 | 0,48 |
| $1500 / 5$ |  |  | 0,02 | 0,02 | 0,03 | 0,04 | 0,05 | 0,06 | 0,08 | 0,10 | 0,13 | 0,16 | 0,19 | 0,32 |
| $2000 / 5$ |  |  |  |  | 0,02 | 0,03 | 0,04 | 0,05 | 0,06 | 0,07 | 0,10 | 0,12 | 0,14 | 0,24 |
| $2500 / 5$ |  |  |  |  |  | 0,02 | 0,03 | 0,04 | 0,05 | 0,06 | 0,08 | 0,10 | 0,12 | 0,19 |
| $3000 / 5$ |  |  |  |  |  |  | 0,02 | 0,03 | 0,04 | 0,05 | 0,06 | 0,08 | 0,10 | 0,16 |
| $4000 / 5$ |  |  |  |  |  |  |  | 0,02 | 0,03 | 0,04 | 0,05 | 0,06 | 0,07 | 0,12 |
| $5000 / 5$ |  |  |  |  |  |  |  |  | 0,02 | 0,03 | 0,04 | 0,05 | 0,06 | 0,10 |
| $6000 / 5$ |  |  |  |  |  |  |  |  |  | 0,02 | 0,03 | 0,04 | 0,05 | 0,08 |

If the size of the stage, the current transformer, or the rated current of the control system does not meet the values as given in above table, the equation on page 26 has to be applied in order to determine the $\mathrm{c} / \mathrm{k}$ value.

### 5.11 Switching Sequence

When the automatic $\mathrm{c} / \mathrm{k}$ identification is switched on every optional switching sequence is possible.
Necessary condition: When the optional switching combinations are sorted according to their capacity, the capacity difference between two successive combinations may only be 1.2 times the capacity of the smallest stage.
If the automatic $\mathrm{c} / \mathrm{k}$ identification is switched off, the switching sequence (switching programme) can be reset to the following combinations of capacitor stages:
1:1:1:1:1... 1:1:2:4:4... 1:2:3:4:4...
1:1:2:2:2... 1:1:2:4:8... 1:2:3:6:6...
1:1:2:2:4... 1:2:2:2:2... 1:2:4:4:4...
1:1:2:3:3... 1:2:3:3:3... 1:2:4:8:8...
The smallest capacitor stage is always " 1 ", the subsequent stages are either the same ( $1: 1: 1 \ldots$ ) or are larger. In the second line above a more accurate result can be achieved with the same number of switching contactors.

When the automatic $\mathrm{c} / \mathrm{k}$ identification is switched off, the smallest capacitor stage ("1") must be connected to the first control output of the connecting terminal. All other stages follow according to their capacity. In the case of fixed stages being used, the smallest stage has to be connected following the last fixed stage.

### 5.12 Number of Contactors used

When the automatic $\mathrm{c} / \mathrm{k}$ identification is switched off, any value between 1 and 12 can be programmed. If, for example, there are five stages in a capacitor bank, these stages are connected to the control outputs " 1 " to " 5 " and the number of the control outputs is programmed to " 5 " in order to prevent the control relay from activating control outputs which have not been connected.

The size of the capacitor stages has no influence on this setting.

### 5.13 Specifying fixed Stages

The Control Relay EMR 1100 allows the first three control outputs to be treated as fixed stages. Fixed stages are stages which are not included in the normal control cycle but are switched on immediately after the control relay is switched on and always remain switched on. The set discharge period is maintained. The target power factor setting is ignored.
The following settings are possible:
0 = no fixed stages
1 = control output 1 is fixed
2 = control outputs 1 and 2 are fixed
3 = control outputs 1 to 3 are fixed
The switching sequence does not take into account the fixed stages.

### 5.14 ON/OFF Connection Identification

The control relay has an automatic connection identification feature. (Refer to section 2.1)

ON: The connection recognised by the control relay can be read under mode number -15- in accordance with table 2. (not changeable)

OFF: The connection must be manually programmed as per table 2.

### 5.15 Connection Mode

Usually, the connection mode should be set to automatic operation. If, however, the control relay failed to determine the connection mode after 15 minutes due to high load changes or phase imbalances, it is possible to enter the connection mode manually as per table 2 .

### 5.16 Setting Capacitor Discharge Time

In order to ensure that after switching-off, a capacitor stage is not switched on again before the capacitor has been sufficiently discharged, the switch-off time can be adjusted to the specific needs (discharge mode).
The discharge time can be set between 5 and 900 seconds.

### 5.17 Setting Cyclic/Non-Cyclic Switching Rotation

In certain cases when there are filtered and non-filtered stages within one system, it is necessary to ensure that the control relay does not operate cyclically. For such applications this feature can be disabled.
On and off have the following meanings:
ON: Small number of switches, cyclic switching is enabled on all levels.
OFF: No cyclic switching; the stages within each level are switched on.

### 5.18 Current Transformer (CT) Ratio

In order to display the currents as actual values, the ratio between the primary current and the secondary current of the current transformer used must be entered. If the current transformer ratio is not set the value displayed must be multiplied by the CT ratio. Values between 1 and 7000 can be entered (eg. 1000A/5A $\rightarrow 200$ ).

### 5.19 Voltage Transformer Ratio

If a voltage transformer is used within the measuring circle the voltage transformer ratio must be entered in order to scale the display of missing kvar to reach the target power factor correctly.
The primary/secondary voltage transformer ratio is set between 1 and 300 . If no voltage transformer is present, the value " 1 " must be entered.

### 5.20 FRAKO Power Bus Address

If the relay is connected to the FRAKO Power Bus it has to be given its own bus address between 1 and 125. This address may only be given once within the bus system.
In case of big systems we advise the use of "System-SW" software to programme the bus address. This software is supplied together with the Bus Central Unit or can be ordered separately.
A bus address can be adjusted also at the basic version (-S). An update for a full version is only via the bus system possible (an update-key is needed).

### 5.21 Setting $5^{\text {th }}$ Harmonic Threshold

The Control Relay EMR 1100 has a harmonic monitoring system for the $5^{\text {th }}, 7^{\text {th }}$, $11^{\text {th }}$, and $13^{\text {th }}$ voltage harmonics. If the limiting value is exceeded, there is an alarm signal, i.e. the alarm contact closes and the "Alarm" LED illuminates for as long as the limiting value is exceeded. The "Harmonic" LED flashes until the alarm is switched off. The order and the maximum value of the harmonics which have been exceeded, beginning with the maximum deviation, are displayed by multiple pressing of the "Set" button. The "Set" button must be pressed repeatedly until the "Harmonic" LED goes out.

### 5.22 Setting $7^{\text {th }}$ Harmonic Threshold

Setting of the limiting value for the $7^{\text {th }}$ harmonic.

### 5.23 Setting $11^{\text {th }}$ Harmonic Threshold

Setting of the limiting value for the $11^{\text {th }}$ harmonic.

### 5.24 Setting $13^{\text {th }}$ Harmonic Threshold

Setting of the limiting value for the $13^{\text {th }}$ harmonic.

### 5.25 Harmonic Over-Current Alarm Signal

The Control Relay EMR 1100 is able to determine the ratio between the actually measured RMS current and the nominal current ( $50-60 \mathrm{~Hz}$ ) of the capacitor. If this ratio is exceeded by the factor set for at least one minute due to harmonics and the resulting resonance phenomenon, the control relay switches off all stages. At the same time an alarm is signalised.
If "H.-AL." is selected, become with a voltage harmonics alarm (Prog. -21- to -24-) within 5 seconds all stages switched off.
After the alarm has been acknowledged it takes approx. 4 minutes until the necessary capacitor stages are switched on.

By pressing the "Set" button the peak value is displayed.

## Notice: <br> When exclusively filtered stages are being used, see also section 6.3.3.

### 5.26 Setting Threshold for Number of Switchings Alarm

In order to support the maintenance of the unit the EMR 1100 provides an internal counter for each switching output.
During manual operation the present count for each stage can be displayed. (see section 6.2).

If the maximum of switching actions is chosen the control relay displays the need for maintenance. The stage which has exceeded the limit (e.g. " 5 r. 4 " for the $4^{\text {th }}$ stage) flashes on the display (approx. every 10 seconds). At the same time an alarm is signalised. How to put out the alarm is explained in 5.27.

The required number of switches is to be divided by 1000 before being entered.
That means that entering 100 evokes an alarm at 100,000 switches of one stage.

The stage alarm signals have no influence on the control behaviour/ performance of the relay.

### 5.27 Reseting Switching Counter

In mode -27- the switching counters can be reset altogether or separately.
When choosing mode -27- the display shows " 0 ". With the "+" and "-" buttons a stage number between 1 and 12 or "all" can be chosen. Leaving the programing section by pressing the "man/set" button resets the count of the displayed stage. By setting "all" all counts are reset.
If you do not want to reset any counter "0" has to be set befor pressing the "man/set" button.

### 5.28 Suppressing the Power Factor Alarm

As already described the control relay tries to reach its programmed control band. If this, however, is not possible due to lack of capacitor stages available, an alarm is signalised after several minutes (depending on the size of the difference). In case of a capacitive cos-phi outside the band range the alarm signal functions as well. When setting "OFF" the alarm is suppressed.

### 5.29 Total kvar Display

Provided the current transformer ratio has been entered, the total kvar detected at measured voltage will appear on the display, when "Set" is pressed in Mode -29-.

## 6. Operation

### 6.1 Modes of Display

The power factor display is independent of the control relay operation and can be reprogrammed at any time. To the right of the four and a half character digital display there are three LEDs indicating which display mode is active, either "cos phi", "Ampere", or "Harmonic".

Five modes of display can be selected by pressing the appropriate button:

### 6.1.1 Power Factor

The "Power Factor" display mode is the standard display and can be activated from another mode of display by pressing the buttons "IQ", "IP", or "Harm". The symbols "+" for ind. and "-" for cap. show whether the power factor is inductive or capacitive.
The LED "Regen" indicates that generative active power is fed back into the mains. Active and reactive currents are measured seprarately. The power factor (cos phi) display value is the result of a mathematical calculation, which ensures accuracy over the entire range down to values close to 0 . The minimum apparent current for a correct power factor (cos phi) display is approx. 0.02 A . When the apparent current falls below 0.02 A for three consecutive measurements one capacitor stage is
switched off and if there is no change in the measured current, all remaining stages are switched off and " $1=0$ " appears on the display.

### 6.1.2 Reactive Current



The display indicates the reactive current portion in the current transformer circuit. The "+" for ind. or "-" for cap. indicate whether the reactive current is inductive or capacitive. The LED "Ampere" lights up. From this mode of display the compensation effect of the capacitor stages e.g. by adding or removing capacitor stages manually, can be monitored. If the current transformer ratio (CT) is programmed via the set mode, the actual reactive current on the primary side of the CT is displayed. Otherwise the current portion is displayed and has to be multiplied by the CT ratio to obtain the actual value.
Pres "IQ", "IP", or "Harm" buttons to exit this mode of display.

### 6.1.3 Active Current



The display shows the active current on the fundamental oscillation in the current transformer (CT) circuit. The LED "Ampere" lights up.
The current direction is also displayed which is helpful during tests. The LED "Regen" shows that the generative active power is fed back into the mains. If the CT ratio is programmed into the relay, the actual active current is displayed; otherwise the current portion is displayed and must be multiplied by the CT ratio to obtain the actual value.

Press "IQ", "IP", or "Harm" buttons to exit the display.

### 6.1.4 Apparent Current



Pressing the "IQ" and "IP" buttons simultaneously activates the display. The LED "Ampere" lights up. If the CT ratio is programmed into the relay, the actual apparent current on the fundamental oscillation in the current transformer (CT) circuit is displayed; otherwise the current portion is displayed and must be multiplied by the CT ratio to obtain the actual value.

Press "IQ", "IP", or "Harm" buttons to exit the display.

### 6.1.5 Harmonics $\left(5^{\text {th }}-13^{\text {th }}\right)$

## Harm

This display shows the $5^{\text {th }}, 7^{\text {th }}, 11^{\text {th }}$, and $13^{\text {th }}$ harmonics on voltage. The previous harmonic reading appears on the display (in \%) and the LED "Harmonic" lights up. By pressing the "+" or "-" buttons several times the portions of the $5^{\text {th }}, 7^{\text {th }}, 11^{\text {th }}$, and $13^{\text {th }}$ harmonics are subsequently displayed either in ascending or descending order. For example. if " 5.2 .9 " is displayed this means " 5 th harmonics $=2.9 \%$ ".
Press the "Harm" button to exit the display.

### 6.2 Manual Operation

## Man <br> Set

When the "man/Set" button is pressed for more than 3 secs, the control relay switches to manual operation and the LED "manual" begins to flash. The capacitor stages can be switched on or off by pressing the "+" or "-" button.
When the "+" button is pressed once, "1.ON" appears on the display until the control relay has switched on the first
stage after approx. 10 secs provided no further buttons have been pressed. If the first stage was already switched on
"1.OFF" will appear on the display until the control relay has switched off the first stage after approx. 10 secs. Then the display will change to the last displayed value.
While waiting the switching counter of this stage will be displayed for a short moment. The displayed value is multiplied by 0.001 and is indicated as far as possible as a decimal. That means for example:
" 0.350 " is equivalent to 350 switches.
By pressing the "+" button several times the stages $2-12$ will appear in ascending sequence on the display. They can be switched on/off in the same way.
By pressing the "-" button once "12.0N" appears on the display until the control relay has switched on the 12th stage after approx. 10 secs. If the 12th stage was already switched on "12.OFF" will appear on the display until the control relay has switched off the 12th stage after approx. 10 secs. Then the display will change to the last displayed value. By pressing the "-" button several times the stages 11-1 will appear on the display in a descending sequence. They can be switched on/off in the same way.
In manual mode, the programmed switching off time (discharge time) is taken into consideration, i.e. when switching on a
stage which was previously switched off the switching-off time is the same as the discharge time. If a stage was identified as a zero stage (without power) the corresponding numbers would indicate this by flashing.
Press "Man/Set" button to exit manual mode.

### 6.3 Alarms

The potential-free alarm contact (a/b) closes whenever the operating voltage is not applied. In the case of the correct operating voltage, the contact closes if there is an alarm. The conditions for an alarm can be seen in section 6.3.1 to 6.3.6 below. The LED "alarm" lights up for as long as a state of alarm exists. When an alarm is signalised, an alarm marker is put into action (LEDs "Power Factor", "Ampere", or "Harmonic" blink).
The alarm markers remain active after the alarm until they are acknowledged by pressing the "Set" button. After acknowledgement the flashing alarm marker goes out.
The alarm signals have no influence on the control behaviour/performance of the relay.

### 6.3.1 Power Factor Alarm

If the threshold values set for "switch-on" and "switch-off" are exceeded and no further change can take place in the output
stages, the alarm signal functions (except for the cos-phi alarm being switched-off; see mode -28-). By pressing the "Set" button the amount of capacitive and reactive power missing to reach the target power factor flashes on the display.
Pressing the "Set" button again shows the actual power factor on the display and the alarm marker "Power Factor" no longer flashes.

### 6.3.2 Harmonic Alarm

When the programmed threshold values are exceeded the alarm goes off.
By pressing the "Set" button several times the display shows the order and the maximum values of the exceeded harmonics starting with the maximum deviation.
The button "Set" must be pressed repeatedly until the "Harmonic" alarm no longer flashes.

### 6.3.3 Over-current alarm

If the ratio between the actually measured RMS current and the nominal current of the capacitor has exceeded the programmed value for one minute, the alarm goes off and all stages are switched off.

After the alarm has been acknowledged it takes approx. 4 minutes until the neces-
sary capacitor stages are switched on again.

By pressing the "Set" button the display shows the maximum value of the factor by which the RMS current has exceeded the nominal current.
By pressing the "Set" button again the display shows the actual power factor and the alarm marker "Ampere" no longer flashes. (See also section 5.25 , page 30 )

## Notice:

The over-current ratio is a mathematically determined value and therefore cannot be applied to filtered systems.
If "H.-AL." is selected (Prog. -25-) only the voltage harmonics are supervised. The over-current ratio is not considered.

### 6.3.4 "U=0" Alarm

If there is an interruption in the measurement voltage path, the control relay switches off all stages after about 1 sec . and displays " $\mathrm{U}=0$ ".
At the same time, the alarm contact closes and the "Alarm" LED lights up for as long as there is no voltage applied to the measurement input terminals of the control relay.

### 6.3.5 "C=0"-Alarm

If the relay does not identify a capacitor stage during the process of automatic terminal and stage current identification an alarm is signalised and the display shows " $\mathrm{C}=0$ ".
The identification process is carried on despite the alarm.

### 6.3.6 "I=0" Alarm

If there is an interruption in the current path for at least 3 secs., the control relay immediately switches off a capacitor stage.

If there is no change in the current as a result, the stages which are still on are switched off.
There is no alarm.

## 7. Technical Data

## Mode of Connection:

Phase/Phase connection or
Phase/Neutral connection
Current via current transformer in optional phase (Figure 3, page 12).

## Fusing:

External, max. 4A

## Operating Voltage:

| Supply <br> voltage | Mains terminal <br> voltage | Absolute permissible/ <br> threshold values |
| :---: | :---: | :---: |
| $230 \mathrm{~V} \sim$ | $220 \mathrm{~V} \sim$ to $240 \mathrm{~V} \sim$ | $198 \mathrm{~V} \sim \ldots 264 \mathrm{~V} \sim$ |
| $400 \mathrm{~V} \sim$ | $380 \mathrm{~V} \sim$ to $420 \mathrm{~V} \sim$ | $342 \mathrm{~V} \sim \ldots 462 \mathrm{~V} \sim$ |

## Voltage Path:

Voltage input 100V~ ... 690V~

## Frequency:

$50 \mathrm{~Hz} / 60 \mathrm{~Hz}(48$ to 62 Hz$)$

## Consumption:

approx. 13VA

## Current Path:

For current transformer .../1A~ to ... /5A~

## Consumption in Current Path:

max. 1.8 VA at $5 \mathrm{~A} \sim$ rated current of the CT

## Control Contacts:

12 potential-free relay contacts

## Loading Capacity of the Control

 Contacts:Switching voltage:
380 VAC (acc. to VDE 0110 part B)
250 VAC (acc. to VDE 0110 part C)
Switching current up to $2 \times 5$ A max.
Switching load up to 1800 VA max.
Fault Signal Contacts:
Loading capacity 250V~, 3A
Temperature Range:
$-20{ }^{\circ} \mathrm{C}$ to $+60{ }^{\circ} \mathrm{C}$

## Enclosure:

Terminals IP 20
Casing IP 50
When using the sealing ring IP 54
(see accessories)

## No-Voltage Trip (Undervoltage Monitoring):

For a voltage loss of longer than 15 ms all capacitor stages connected are switched off. After voltage is restored the control relay switches the required stages on.

## Zero Current Trip:

For a current loss of longer than 3 secs capacitor stages connected are switched off. After current is restored the control relay switches the required stages on.
Interfaces (operation mode optional):
FRAKO Power Bus ©:
For connection to the FRAKO Energy Management System according to EN 50170 (P-NET) Feldbus standard RS 485, 76,8 kbit/s
RS-232-interface:
Via RS232-Adapter (accessory) for direct connection to PC (for using PC software "EMR-SW") 19200 Baud

## Terminals:

Plug-in connector blocks
(supplied with the control relay)
Enclosure Material:
Black synthetic plastic, flame resistant to UL-94, Class V0

## Weight:

ca. 1.2 kgs
Mounting Position:
as desired

## Front Panel Dimensions:

$144 \times 144$ mm (to DIN 43 700)

## Panel Cut Out:

$138 \times 138$ mm (to DIN 43 700)

## Mounting Depth:

105 mm

## Fastening:

Through the front panel by means of a screwdriver

## Operating Elements:

Foil keyboard with 4 buttons

## LED Indicators:

18 LEDs
$41 / 2$ character digital display
Design:
according to:

- EN 50 081-1
- EN 50 082-2
- EN 61010 (VDE 0411 part 1) Protection Class II (if insulated fixing screws are used)
Accessories:
protection kit for protection class II / IP 54 item no. 20-50014
Software "EMR-SW".... item no. 20-10312
update full verion.......... item no. 20-50013
RS232-Adapter (PC).... item no. 20-10310
RS232-Adapter (Modem)
item no. 20-10309


## 8. Trouble-Shooting

| Pos. | Faults | Possible Causes | Necessary Action |
| :---: | :---: | :---: | :---: |
| 1 | Control relay does not function, digital display remains blank. | There is either no voltage or the wrong voltage has been applied to the control relay. | Check whether the correct operating voltage is applied to the control relay. |
| 2 | " $U=0$ " flashes on the display. | The voltage applied to the voltage path of the control relay is too small. | Check whether the correct voltage has been applied to the voltage path of the control relay. |
| 3 | Relay does not respond to manual operation although it has voltage and digital display is operational. | End of delay time of approx. 10 secs. has not been observed. | For example, if "1. ON" appears on the display wait until the control relay has switched on the first stage. |
|  |  | Relay was not in manual mode. | "Man" button must be pressed leading to flashing of the LED "manual". |
| 4 | Stage display (LED 1-12) lights up but capacitor contactors are not activated | Control circuit is not connected properly or there is no control voltage | Check the control circuit according to the circuit diagram and check fuses. |
|  |  | There is no neutral on the contactors. |  |
| 5 | Control relay does not complete the automatic identification procedure | Unstable power supply (power factor fluctuation). | Wait for power supply to stabilize or manually set c/k factor and mode of connection. |
| 6 | During automatic adjustment process "C=0" flashes on the display. | Fault in control circuit (contactors do not switch) | Check control circuit according to the circuit diagram; check fuses. |
|  |  | Fuses of the capacitor stages are defective or missing. | Check if capacitors are energized after switching. |
|  |  | Current transformer is in the wrong place. | Check if the position of current transformer corresponds to the circuit diagram. |
| 7 | " $=0$ " flashes on the display. | Current transformer circuit interrupted or there is no current flowing on the secondary side. | Use ammeter to check current on secondary side of CT. ( $1 \mathrm{~min}>=0.02 \mathrm{~A}$ ). |
|  |  | The current flowing on the secondary side of the CT is too small. | $\begin{aligned} & \text { (I } \min >=0.02 \mathrm{~A}) \\ & \text { Install smaller current transformer. } \end{aligned}$ |
|  |  | Current transformer is defective. | Check the current transformer. |


| Pos. | Faults | Possible Causes | Necessary Action |
| :---: | :--- | :--- | :--- |
| 8 | Despite inductive load <br> no stages are switched <br> on when relay is in <br> automatic mode. | When programming the <br> control relay, the c/k factor, <br> switching time delay, or <br> discharge time have been set <br> too high. | Check programming of the control <br> relay and change if necessary. |
|  |  | In automatic operation the c/k <br> factor was not correctly <br> detected. | Check the control circuit according to <br> the circuit diagram and repeat the <br> automatic test procedure. |
|  |  | A different current measuring <br> meter (e.g. ammeter) has <br> been connected in parallel <br> with the control relay to the <br> secondary side of the current | All measuring instruments in current <br> path must be connected in series |
| transformer. |  |  |  |

Version V1.52a ab SW 2.06

Notice:

Notice:

## Reactive Power Control Relay EMR 1100 /-S

## Sales Programme

- Active filters
- Reactive power control relays
- Power capacitors for low voltage


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Quality has a Name
We are certified for ISO 9001 and ISO 14001

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[^0]:    Diese Erklarung bescheinigt die Übereinstimmung mit den geinannten Ricitlinien, beinhaltet jedoch keine Zusicherung von Eigenschaften. Die Sicherheitshinweise der mitgelieferten Produkldokumentation sind zu beachten.
    This decleration certify the conformity according the mentioned directives, without any assurence of features. Please note the safety instructions of the attached product documentation.

[^1]:    *) only possible at full version

[^2]:    *) only possible at full version

[^3]:    IMPORTANT NOTICE: Before commissioning of the control relay it has to be ascertained that it is not possible to touch the connecting terminals (e.g. by means of a locked door or covering).
    The control relay must be kept voltage free during wiring and installation works.

